Crossing Reduction for Hierarchical Graphs with Intra-Level Edges

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Abstract. In drawings of hierarchical graphs generated by the conventional Sugiyama framework the vertices are positioned on multiple horizontal level lines. This drawing style which allows edges only between vertices on different levels is well suited for the visualization of a common direction of flow from lower to higher levels in a graph.

In this paper we are interested in reordering the vertices on each level line to increase readability of the drawing, i.e., in reducing the number of edge crossings. As novelty, we additionally allow the existence of edges with both end vertices on a common level, which often occur in practice. Experimentally we found out, that we can save about 30% of the crossings compared to the existing standard heuristic which ignores those edges.

1 Introduction

In hierarchical graph layout vertices are usually drawn on parallel horizontal lines, and edges are drawn as strict y-monotone polylines that may bend when they intersect a level line. The standard drawing framework [12] consists of four phases: cycle removal (reverses appropriate edges to eliminate cycles), level assignment (assigns vertices to levels such that no edge has both end vertices on the same level and introduces dummy vertices to represent edge bends), crossing reduction (permutes vertices on the levels), and coordinate assignment (assigns x-coordinates to vertices, y-coordinates are implicit through the levels). See [7] for an extended overview.

In this paper we are especially interested in the crossing reduction phase to improve readability [10] of the drawing. As novely we allow the existence of *horizontal* edges having both end vertices on a common level and take their crossings into account. This type of level graphs often occurs in practice: for example graphs were the level assignment is already predefined, e. g., by breadth first search (BFS) levels to express distances, or social network graphs [2–4] where the importance (*centrality*) of an *actor* (modeled by a vertex) defines its level.

Preferably we want to draw all edges as straight lines. But at least with vertices having more than two adjacent horizontal edges this is not possible, unless we allowed overlapping of edges and crossings between vertices and edges. To avoid this, cf. Fig. 1, we draw horizontal edges as semicircles with different radii. Further we restrict ourselves to draw the semicircles only above the level lines and not below, what practically makes it easier to attack the problem. Since this leads to three kinds of crossings, our idea is to treat them separately with a standard sifting heuristic, with circular crossing reduction, and a new counting algorithm. Since all three algorithms are some kind of sifting, we interlock them all in a new integrated sifting heuristic.

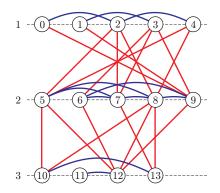


Fig. 1. Level graph example illustrating drawing conventions

This paper is organized as follows: After some necessary preliminaries showing existing algorithms in Sect. 2 we explain in Sect. 3 how to extend sifting also to count crossings generated by horizontal edges.

2 Preliminaries

A k-level graph $G = (V, E, \phi)$ is a graph with a level assignment $\phi: V \to \{1, 2, \ldots, k\}$, which partitions the vertex set into $k \leq |V|$ pairwise disjoint subsets $V = V_1 \cup V_2 \cup \cdots \cup V_k$, $V_i = \phi^{-1}(i), 1 \leq i \leq k$, such that $|\phi(u) - \phi(v)| = 1$ for each vertical edge $\{u, v\} \in E$. Particularly, k = 1 implies that $E = \emptyset$. For $v \in V$ with $\phi(v) > 1$ let $E(v) = \{\{u, v\} \in E \mid u \in V_{i-1}\}$ be the (predecessor) vertical adjacency list. Define $E(v) = \emptyset$, if $\phi(v) = 1$. An ordering of a proper level graph is a partial order \prec of V such that $u \prec v$ or $v \prec u$ iff $\phi(u) = \phi(v)$ for each pair of vertices $u, v \in V$. If the vertex sets V_i are ordered sets (according to \prec), we call G an ordered level graph.

2.1 Sifting with a Crossing Matrix

The most common technique for crossing reduction in level graphs is to only consider two consecutive levels at a time in multiple top-down and bottom-up passes. Starting with an arbitrary ordering of the first level, subsequently the ordering of one level is fixed, while the next one is reordered to minimize the number of crossings in-between. This one-sided two-level crossing reduction problem is \mathcal{NP} -hard [6] and well-studied: Given a 2-level graph $G = (V_1 \cup V_2, E, \phi)$ where V_1 is the set with the fixed ordering, the objective is to compute an ordering of the second level V_2 which causes fewest crossings. As not mentioned otherwise, we restrict ourselves to one-sided two-level crossing reduction in the following.

To face the problem, we use the *sifting* heuristic here, which is slower than simple heuristics like *barycenter* or *median* heuristics [7] but generates less crossings. Barycenter (median) heuristic assigns each vertex of V_2 the barycenter (median) value of its neighbors in V_1 , assuming the positions of vertices in V_1 are numbered from 1 to $|V_1|$ according to \prec . A sorting according to this values defines the ordering among the vertices in V_2 . Sifting was originally introduced as a heuristic for vertex minimization in ordered binary decision diagrams [11] and later adapted for the one-sided crossing minimization problem [9]. The idea is to keep track of the objective function while moving in a sifting step a vertex $u \in V_2$ along a fixed ordering of all other vertices in V_2 and then placing u to its locally optimal position. The method is thus an extension of the greedy-switch heuristic [5], where u is swapped iteratively with its successor. We call a single swap a sifting swap. Executing a sifting step for every vertex in V_2 is called a sifting round. For crossing reduction the objective function is the number of crossings between the edges incident to the vertex under consideration and all other edges. The efficient computation of the crossing count in sifting is based on the crossing matrix. Its $|V_2|^2$ entries correspond to the number of crossings caused by (the edges of) pairs of vertices in a particular relative ordering and can be computed as a preprocessing step in $\mathcal{O}(|E|^2)$ [13,14]. Whenever a vertex is placed to a new position, only a smallish number of updates is necessary which allows a running time of $\mathcal{O}(|V_2|^2)$ for one round. Usually only few sifting rounds (3-5) for reasonable problem instances) are necessary to reach a local optimum for all vertices simultaneously. Thereby the largest reduction of crossings usually occurs in the first round.

2.2 Circular Sifting

However, the asymptotic overall running time of the algorithm described above is $\mathcal{O}(|E|^2+|V_2|^2)$ and too high for our purposes. Thus we apply the heuristic of Baur and Brandes [1] originally used for the \mathcal{NP} -hard [8] circular crossing reduction problem: Reorder the vertices V of a graph G = (V, E) which all are placed on a single circle (e.g., in Fig. 3) to minimize the number of crossings among the straight-line edges in E. Since there is no "circular" ordering, Baur and Brandes define linear orders \prec_{α} by selecting a reference vertex $\alpha \in V$ which is the first of

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the (here counter-clockwise) sequence. For finding the locally optimal position for a vertex $u \in V$ in a sifting step it is sufficient to record the change in crossing count while swapping u with its successor v. This can be done by considering only edges incident to u or v: After a swap exactly those pairs of these edges cross which did not before. All other crossings remain unchanged (let $\chi(\pi)$ be the number of crossings of a drawing π and N(u) be the set of adjacent vertices of $u \in V$):

Lemma 1 (Baur, Brandes). Let $u \prec_u v_p \in V$ be consecutive vertices in a circular layout π and let π' be the layout with their positions swapped, then

$$\chi(\pi') = \chi(\pi) - \sum_{x \in N(u)} |\{ y \in N(v_p) \mid y \prec_x^{\pi} u \}| + \sum_{y \in N(v_p)} |\{ x \in N(u) \mid x \prec_y^{\pi'} v_p \}|$$

At the end of one step, u is placed where the intermediary crossing counts reached their minimum. For efficiency reasons the computation of the change in crossing count is implemented over suffix lengths in ordered adjacency lists.

We adapt the above idea to one-sided two-level crossing reduction, which we call vertical sifting for simplicity. We mainly exchange \prec_{α} by \prec as illustrated in Algorithms 1, 2, and 3 and thus consider the ordering of the neighbors on the fixed level 1. We obtain the same results as with the matrix method, however, without knowing the absolute crossing numbers. Since all three methods are generic and also fit for the following algorithms, Algorithm 2 already contains lines 4 and 8. But up to now these lines can be ignored and the input graphs should be considered as $G = (V_1 \cup V_2, E, \phi)$ for ease of understanding. For efficiency reasons all shown operations should be implemented in place on the graph data structure.

Algorithm 1: SIFTING-ROUND

Input: Ordered two level graph G = (V₁ ∪ V₂, E, H, φ)
Output: Updated ordering of V₂
1 foreach u ∈ V₂ do
2 L V₂ ← SIFTING-STEP(G, u)
3 return V₂

3 Reduction with Horizontal Edges

An extended k-level graph $G = (V, E, H, \phi)$ is a k-level graph (V, E, ϕ) which additionally has horizontal edges $\{u, v\} \in H$ with $\phi(u) = \phi(v)$. For $v \in V_i$ let $H_l(v) = \{\{u, v\} \in H \mid u \prec v\}$ be the left horizontal adjacency list and $H_r(v) = \{\{v, w\} \in H \mid v \prec w\}$ be the right horizontal adjacency list.

Algorithm 2: SIFTING-STEP

Input: Ordered two level graph $G = (V_1 \cup V_2, E, H, \phi)$, Vertex $u \in V_2$ to sift **Output**: Updated ordering of V_2 1 let $v_0 = u \prec v_1 \prec \cdots \prec v_{|V_2|-1}$ denote the current ordering of V_2 2 foreach $v \in V_2$ do Sort $E(v) \subseteq E$ by ascending ordering of V_1 in $\mathcal{O}(|E|)$ time 3 Sort $H_l(v), H_r(v) \subseteq H$ by ascending ordering of V_2 in $\mathcal{O}(|H|)$ time 4 // current and best number of crossings 5 $\chi \leftarrow 0; \chi^* \leftarrow 0$ $\mathbf{6} \ p^* \leftarrow \mathbf{0}$ // best vertex position 7 for $p \leftarrow 1$ to $|V_2| - 1$ do $l \leftarrow \text{UPDATE-HORIZ-ADJ}(G, u, v_p)$ 8 $\chi \leftarrow \chi + \text{SIFTING-SWAP-V}(G, u, v_p)$ 9 if $\chi < \chi^*$ then 10 $\chi^* = \chi$ 11 $p^* = p$ 12 13 return $V_2 \leftarrow v_1 \prec \cdots \prec v_{p^*-1} \prec u \prec v_{p^*} \prec \cdots \prec v_{|V_2|-1}$

Algorithm 3: SIFTING-SWAP-V

Input: Ordered two level graph $G = (V_1 \cup V_2, E, H, \phi)$, Swap vertices $u, v_p \in V_2$ Output: Change in crossing count 1 let $x_0 \prec \cdots \prec x_{r-1}$ be the neighbors of u in $V_1, \{x_i, u\} \in E$ **2** let $y_0 \prec \cdots \prec y_{s-1}$ be the neighbors of v_p in $V_1, \{y_j, v_p\} \in E$ **3** $c \leftarrow 0; i \leftarrow 0; j \leftarrow 0$ 4 while i < r and j < s do $\mathbf{5}$ if $x_i \prec y_i$ then 6 $c \leftarrow c + (s - j)$ $i \leftarrow i + 1$ 7 else if $y_i \prec x_i$ then 8 $c \leftarrow c - (r - i)$ 9 $j \leftarrow j + 1$ 10 \mathbf{else} 11 $c \leftarrow c + (s - j) - (r - i)$ $\mathbf{12}$ $i \leftarrow i+1; j \leftarrow j+1$ 13 14 return c

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The one-sided two-level crossing reduction problem on an extended 2-level graph is \mathcal{NP} -hard too, since at least two subproblems, considering only the vertical edges [6] and considering only the horizontal edges [8] are \mathcal{NP} -hard as well. As a consequence, we use extensions of the sifting heuristic for an efficient solution of the problem. To provide a better overview, we first outline the reduction of different crossing types separately.

3.1 Crossings Between Horizontal Edges

We consider overlapping horizontal edges $\{v_1, v_4\}, \{v_2, v_3\} \in H$ with $v_1 \prec v_2 \prec v_3 \prec v_4$ (also if $v_1 = v_2$ and/or $v_3 = v_4$) as not crossing, since we draw them as circular arcs without any crossing (except common end points) instead of straight horizontal lines: For an edge $\{u, v\} \in H$ we use a quadratic spline with an amplitude, i. e., the height of the only control point, raising with the number of vertices between u and v in the given ordering \prec of V_2 . Thereby we take care not to introduce unnecessary "double" crossings between horizontal and vertical edges by restricting the maximum edge amplitude according to the dimension of the drawing. For example, if the edge $\{5, 8\}$ in Fig. 2(a) would have a higher amplitude, it would cross the edge $\{5, 4\}$. Note that we require to draw all horizontal edges completely above the second level line, as will be explained later in Sect. 3.2.

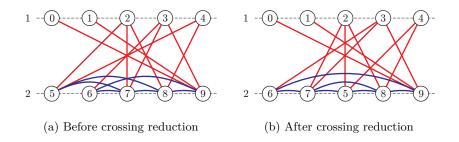


Fig. 2. The first 2 levels of Fig. 1

A straightforward solution to the horizontal crossing reduction problem is the introduction of dummy levels which contain an artificial dummy vertex splitting each horizontal edge. Then, in worst case, the amplitudes of the edges may be pairwise different, what leads up to |H| different dummy levels. As a consequence – to be able to run later a 2-level crossing reduction algorithm which considers all type of crossings – each vertical edge must be split in |H| + 1 segments by |H| new dummy vertices. This prevents not only time efficient processing, but also is obstructive to get a good result, i. e., less crossings, since each of the additionally necessary |H| crossing reduction rounds is a heuristic only and thus not exact.

Thus for *horizontal sifting* we again decided to take the circular sifting algorithm of [1] already used for crossing reduction among vertical edges in Sect. 2.2. Considering the horizontal line of level 2 bent to a circle (see Fig. 3), the circular crossing reduction algorithm fits "out of the box": For one round call Algorithm 1 with line 9 of Algorithm 2 updated to call Algorithm 4 instead of Algorithm 3. Line 3 of Algorithm 2 can be left away in this case. Principally, Algorithm 4 is the same as Algorithm 3 except that the neighbors are on level 2 and the ordering \prec is replaced by \prec_{v_p} , i.e., the ordering of V_2 is different in each swap!

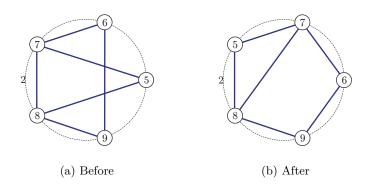


Fig. 3. Circular crossing reduction for horizontal edges for the graph in Fig. 2

With Algorithm 5 we keep the ordered horizontal adjacencies of vertex u up to date during a sifting step. Thus we know the ordering \prec_{v_p} among u's neighbors, since this is nothing else than the concatenation of $H_r(u)$ and $H_l(u)$ (in this order). Therefore we need no reordering for determining the x_i s per swap. The same holds for the y_i s: Algorithm 5 also updates the horizontal adjacencies of vertex v_p , but does in contrast to u not maintain their ordering due to performance restrictions. But we rely on the fact, that an edge $h = \{u, v_p\}$ is always the first of $H_l(v_p)$. This is true, since we build up the sorting of this adjacency list right after u was put on the first position of V_2 in Algorithm 2 and then there never was an update to this ordering. In other words, the ordering of the horizontal adjacencies of all vertices v_p is valid throughout the complete sifting step besides obsolete positions of edges $\{u, v_p\}$. However, this exceptions are irrelevant for the determination of the orderings of the y_i s, since they never contain u.

3.2 Crossings Between Vertical and Horizontal Edges

We restrict horizontal edges only to be routed above the second level line. Otherwise, if we allowed routing on both sides simultaneously, the number of crossings between vertical and horizontal edges would depend on the vertical edges

Algorithm 4: SIFTING-SWAP-H

Input: Ordered two level graph $G = (V_1 \cup V_2, E, H, \phi)$, Swap vertices $u, v_p \in V_2$ **Output**: Change in crossing count

1 let $x_0 \prec_{v_p} \cdots \prec_{v_p} x_{r-1}$ be the neighbors of u in $V_2 - \{v_p\}, \{x_i, u\} \in H$ **2** let $y_0 \prec_{v_p} \cdots \prec_{v_p} y_{s-1}$ be the neighbors of v_p in $V_2 - \{u\}, \{y_j, v_p\} \in H$ **3** $c \leftarrow 0; i \leftarrow 0; j \leftarrow 0$ 4 while i < r and j < s do if $x_i \prec_{v_p} y_j$ then 5 $c \leftarrow c - (s - j)$ 6 $i \leftarrow i+1$ 7 else if $y_j \prec_{v_p} x_i$ then 8 $c \leftarrow c + (r - i)$ 9 $j \leftarrow j+1$ 10 else 11 $c \leftarrow c - (s - j) + (r - i)$ 12 $i \leftarrow i+1; j \leftarrow j+1$ 13

14 return c

Algorithm 5: UPDATE-HORIZ-ADJ

Input: Ordered two level graph $G = (V_1 \cup V_2, E, H, \phi)$, Swap vertices $u, v_p \in V_2$ **Output**: Number of edges between u and v_p , Updated $H_l(u)$, $H_r(u)$, $H_l(v_p)$, and $H_r(v_p)$ as side effect $\mathbf{1} \ l \leftarrow \mathbf{0}$ // number of short horizontal edges 2 while $\{u, v_p\} = getFirst(H_r(u)) \in H$ do 3 $h \leftarrow \text{removeFirst}(H_r(u))$ append $(H_l(u), h)$ 4 // first, since never updated before 5 removeFirst $(H_l(v_p))$ $\operatorname{prepend}(H_r(v_p), h)$ 6 $l \leftarrow l+1$ 7 s return l

to vertices on a third level, which contradicts the pairwise level by level sweep approach.

Like in the above algorithms, swapping vertex u with its successor v_p changes only crossings (here among vertical and horizontal edges) between edges incident to u or v_p . Thus for computing the change in the crossing count we only need the sizes of the six sets $H_l(v)$, $H_r(v)$, E(v) with $v \in \{u, v_p\}$, cf. Fig. 4.

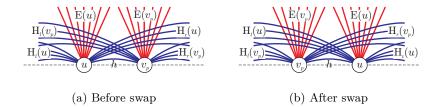


Fig. 4. Crossings among horizontal and vertical edges

Neglecting potentially existing edges $h = \{u, v_p\} \in H$ which are a non contributing special case, we obtain (1) as change in crossing count when swapping u and v_p . The correctness follows again from the invariant that after a swap exactly those pairs of horizontal (except h) and vertical edges cross which did not before.

$$(|H_r(v_p)| - |H_l(v_p)|) \cdot |E(u)| + (|H_l(u)| - |H_r(u)|) \cdot |E(v_p)|$$
(1)

Thus for *mixed sifting* a complete round can be started by calling Algorithm 1 and updating line 9 of Algorithm 2 to call Algorithm 6. Line 3 of Algorithm 2 needs not to be executed here. Please note that the horizontal adjacency updates caused by a swap are done prior to a call of Algorithm 6. Thus l has now to be subtracted from $H_l(u)$ and $H_r(v_p)$ instead of $H_r(u)$ and $H_l(v_p)$.

Algorithm 6: SIFTING-SWAP-HV
Input : Ordered two level graph $G = (V_1 \cup V_2, E, H, \phi)$, Swap vertices $u, v_p \in V_2$, Number of short edges $l = \{\{u, v_p\} \in H\} $ Output : Change in crossing count
1 return $((H_r(v_p) - l) - H_l(v_p)) \cdot E(u) +$ 2 $((H_l(u) - l) - H_r(u)) \cdot E(v_p) $

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3.3 All Crossings

The modular design of the above algorithms now pay off: For *extended sifting* we call Algorithm 1 with an updated line 9 of Algorithm 2 in order to call Algorithm 7, where we simply add the three independent changes in crossing counts. However, other formulas preferring some type of crossings at the expense of more crossings of other types are possible, e.g., the usage of weighting factors.

Algorithm 7: SIFTING-SWAP-EXT	
Input : Ordered two level graph $G = (V_1 \cup V_2, E, H, \phi)$, Swap vertices $u, v_p \in V$ Output : Change in crossing count	1/2
1 $c_1 \leftarrow \text{SIFTING-SWAP-V}(G, u, v_p)$ 2 $c_2 \leftarrow \text{SIFTING-SWAP-H}(G, u, v_p)$ 3 $c_3 \leftarrow \text{SIFTING-SWAP-HV}(G, u, v_p)$ 4 return $c_1 + c_2 + c_3$	

Theorem 1 shows, that we obtain the same time bound as sifting for a graph $G = (V, E, \phi)$ considering only vertical edges or for a graph G = (V, H) considering only horizontal edges.

Theorem 1. One round of extended one-sided sifting on an extended 2-level graph $G = (V, E, H, \phi)$ needs $\mathcal{O}(|V| \cdot (|E| + |H|))$ time.

Proof. For running time calculations, we assume w.l.o.g. that there are no isolated vertices. They can be removed in preprocessing step and added again in postprocessing since their positions have no influence on the crossing number.

One round of vertical resp. horizontal sifting needs $\mathcal{O}(|V||E|)$ resp. $\mathcal{O}(|V||H|)$ time according to Theorem 3 of [1]. One round of mixed sifting needs $\mathcal{O}(|V||H|)$ time, since one step needs $\mathcal{O}(|H|)$ time: The initial sorting of the horizontal adjacency in Algorithm 2 can be done in $\mathcal{O}(|H|)$ by traversing the vertices of V_2 in order and adding each to the adjacency list of its right/left neighbors. One of the $|V_2|$ sifting swaps needs constant time.

The interlocked execution is possible, since the only updates to the horizontal adjacency list are done by Algorithm 2, thus the algorithms mutually don't bias.

3.4 Sweep over all Levels

According to our experience, the quality of sifting does not depend much on the quality of the initial vertex ordering. However, a "bad" initialization raises the number of needed sifting rounds and thus the absolute running time. Thus it maybe useful to apply at least some rounds of horizontal sifting to V_1 to get a practical initial ordering.

In the top-down sweep we reorder the levels i from 2 to k by consecutively applying our extended one-sided two-level crossings reduction on the fix ordered set V_{i-1} and on the permutable set V_i . In the subsequent bottom-up sweep we reorder the levels i from k-1 down to 1 by consecutively applying the two-level algorithm on the fix ordered set V_{i+1} and the permutable set V_i . But bottom-up we have a different situation, since the horizontal edges are below the current level i and cross edges from level i and i-1, see Fig. 5 for an example. However, the formula for crossings of horizontal and vertical edges (1) does not depend on any vertex ordering different to that on level i and especially does not depend on that of level i-1. Thus we count the change in the number of crossings of the horizontal edges of level i with the vertical edges between level i and i-1during a swap. For this we let for every $v \in V_i$ be $E(v) = \{(x, v) \mid x \in V_{i-1}\}$ instead of $\{(y, v) \mid y \in V_{i+1}\}$ in Algorithm 6, which then does nothing else than it does when executed during a top-down sweep. After some iterations, say 10, of top-down with subsequent bottom-up sweeps the algorithm terminates.

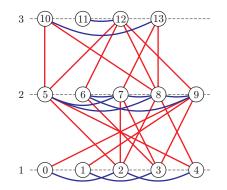


Fig. 5. Bottom-up sweep for the graph in Fig. 1

4 Experimental Results

To analyse the performance of one sifting round of our one-sided two-level crossing reduction heuristics, we have implemented them in Java. Further, we have realized the corresponding standard sifting algorithm which uses a crossing matrix to compare its practical running time with the sifting algorithm of [1]. We have tested the implementations using a total number of 13750 random graphs: 25 graphs for each combination of the parameters $|V_1| = |V_2| \in \{50, 100, 150, \ldots, 1100\}, |E|/|V_2| \in \{1, \ldots, 5\}, \text{ and } |H|/|V_2| \in \{1, \ldots, 5\}.$

Figure 7 and 8 confirms that it makes sense to consider all types of crossings simultaneously, since the algorithm generates (as expected) fewer crossings than standard sifting, experimentally by a factor of 0.7. This is a very encouraging result, since the differences in absolute running times between our extending sifting and the existing standard vertical sifting and horizontal sifting, i. e., the running time of mixed sifting, are negligible in practice even on larger graphs, see Fig. 6. Just to give a feeling, e. g., the running time of extended sifting on a graph with $|V_1| = |V_1| = |E| = |H| = 10^4$ is about 13 minutes.

5 Conclusion

We extended the well known sifting heuristic for crossing reduction to extended level graphs. Ignoring self loops which do not affect the crossing number, our algorithm works out of the box also on multi graphs within the same time complexity.

As far we only use a random initial ordering of the vertices, but the quality of the ordering produced by extended sifting is not independent of the quality of the initial orderings of all levels. Thus it may be helpful to use some extensions of fast and simple heuristics, e. g., barycenter or median [7] heuristics, to reduce the crossing count of the input.

Future research on this topic can be heuristics, which use the freedom of routing horizontal edges above and below their level line and not restricting them to one side.

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A Benchmark Results

The following figures provide benchmark results comparing the heuristics to reduce crossings: vertical sifting (CS with crossing matrix, VS without), horizontal sifting (HS), mixed sifting (MS), and extended sifting (ES). All benchmarks were run on a 2.6 GHz Pentium PC under the Java 2 platform 5.0 from Sun Microsystems, Inc.

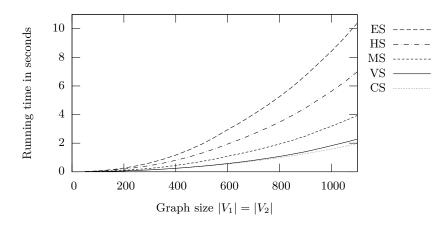


Fig. 6. Benchmark: running times

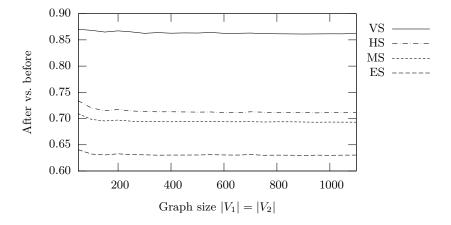


Fig. 7. Benchmark: total crossing numbers

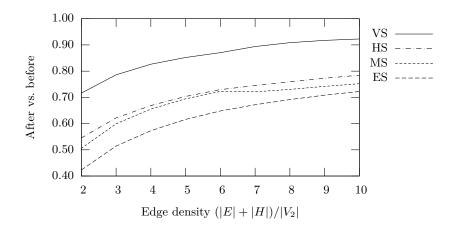


Fig. 8. Benchmark: total crossing numbers

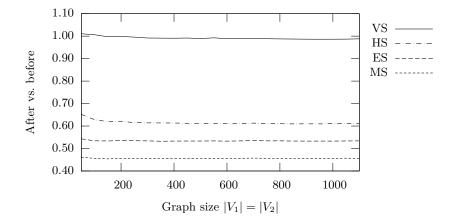


Fig. 9. Benchmark: numbers of crossings between vertical and horizontal edges

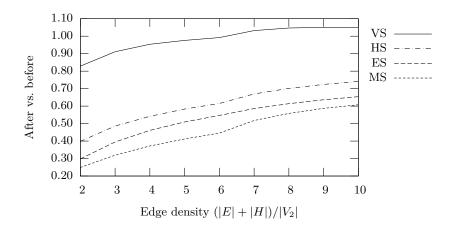


Fig. 10. Benchmark: numbers of crossings between vertical and horizontal edges

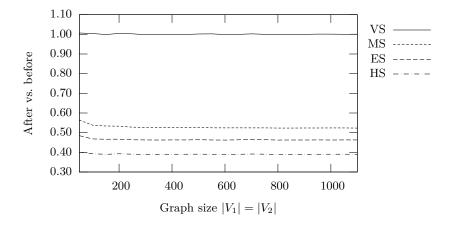


Fig. 11. Benchmark: numbers of crossings between horizontal edges

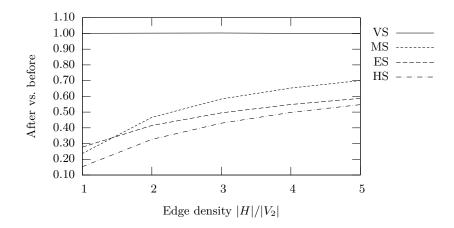


Fig. 12. Benchmark: numbers of crossings between horizontal edges

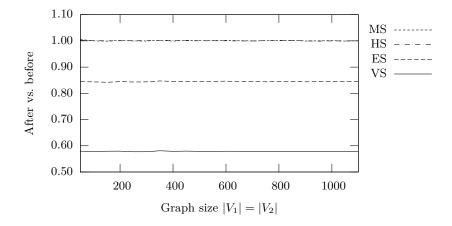


Fig. 13. Benchmark: numbers of crossings between vertical edges

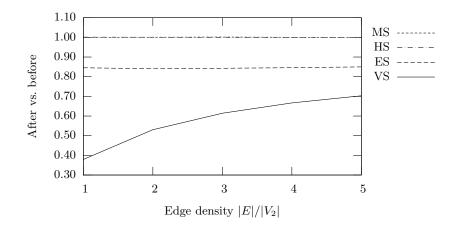


Fig. 14. Benchmark: numbers of crossings between vertical edges